

L Number	Hits	Search Text	DB	Time stamp
-	7225	camera and (piezoelectric or piezo-electric)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 17:09
-	87	camera and ((piezoelectric or piezo-electric) adj drive)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:04
-	0	20010017665.URPN.	USPAT	2004/05/04 12:05
-	0	2001211676.URPN.	USPAT	2004/05/04 12:08
-	3199	(camera and (piezoelectric or piezo-electric)) and computer	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:10
-	1547	((camera and (piezoelectric or piezo-electric)) and computer) and rotate\$2	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:11
-	636	((((camera and (piezoelectric or piezo-electric)) and computer) and rotate\$2) and vibration\$2	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:11
-	533	(((((camera and (piezoelectric or piezo-electric)) and computer) and rotate\$2) and vibration\$2) and axis	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:12
-	150	((((((camera and (piezoelectric or piezo-electric)) and computer) and rotate\$2) and vibration\$2) and axis) and spher\$4	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:12
-	11	((((((((camera and (piezoelectric or piezo-electric)) and computer) and rotate\$2) and vibration\$2) and axis) and spher\$4) not (camera and ((piezoelectric or piezo-electric) adj drive))) and tangential	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:13
-	147	((((((((camera and (piezoelectric or piezo-electric)) and computer) and rotate\$2) and vibration\$2) and axis) and spher\$4) not (camera and ((piezoelectric or piezo-electric) adj drive)))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:17
-	71	ball adj camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 16:51
-	2547	(camera and (piezoelectric or piezo-electric)) and vibration\$2	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:22
-	1600	((camera and (piezoelectric or piezo-electric)) and vibration\$2) and axis	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:22
-	898	((((camera and (piezoelectric or piezo-electric)) and vibration\$2) and axis) and rotation	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:25

-	0	((camera and (piezoelectric or piezo-electric)) and vibration\$2) and axis) and rotat\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:26
-	1148	((camera and (piezoelectric or piezo-electric)) and vibration\$2) and axis) and rotat\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:26
-	75	((camera and (piezoelectric or piezo-electric)) and vibration\$2) and axis) and rotat\$3) and fulcrum	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:32
-	522	actuator with (piezoelectric or piezo-electric) with rotat\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:33
-	63	actuator with (piezoelectric or piezo-electric) with rotat\$3 with axis	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:33
-	2	("3899728" "4727278").PN.	USPAT	2004/05/04 12:42
-	10	4983875.URPN.	USPAT	2004/05/04 12:44
-	3	("4408832" "4422002" "4523120").PN.	USPAT	2004/05/04 12:46
-	33	4727278.URPN.	USPAT	2004/05/04 12:46
-	19	("3487239" "3544202" "3569718" "3902084" "4019073" "4087715" "4195243" "4202605" "4400641" "4422002" "4453103" "4468583" "4523120" "4622483" "4727278" "4736132" "4775815" "4785177" "4798989").PN.	USPAT	2004/05/04 12:51
-	36	5043621.URPN.	USPAT	2004/05/04 12:51
-	2019	(310/311).CCLS.	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:57
-	20	((310/311).CCLS.) and camera	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:55
-	321	((310/311).CCLS.) and rotat\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:57
-	7	((310/311).CCLS.) and rotat\$3) and sphere	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 12:57
-	7	(US-4983875-\$ or US-4727278-\$ or US-5416392-\$ or US-6121568-\$ or US-5696421-\$ or US-5043621-\$).did. or (US-20010017665-\$).did.	USPAT; US-PGPUB	2004/05/04 16:36
-	1	((US-4983875-\$ or US-4727278-\$ or US-5416392-\$ or US-6121568-\$ or US-5696421-\$ or US-5043621-\$).did. or (US-20010017665-\$).did.) and coupled-resonance	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 16:32

-	1	((US-4983875-\$ or US-4727278-\$ or US-5416392-\$ or US-6121568-\$ or US-5696421-\$ or US-5043621-\$).did. or (US-20010017665-\$).did.) and coupled adj resonance	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 16:32
-	414	coupled adj resonance	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 16:32
-	8	coupled adj resonance with piezoelectric	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 16:33
-	142551	"7" and camera	USPAT; US-PGPUB	2004/05/04 16:36
-	3	((US-4983875-\$ or US-4727278-\$ or US-5416392-\$ or US-6121568-\$ or US-5696421-\$ or US-5043621-\$).did. or (US-20010017665-\$).did.) and camera	USPAT; US-PGPUB	2004/05/04 16:36
-	2339	crp	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 16:51
-	395	crp and resonance	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 16:51
-	14	(crp and resonance) and piezoelectric	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 16:51
-	170018	piezoelectric or piezo-electric	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 17:09
-	7887	(piezoelectric or piezo-electric) and ball	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 17:10
-	1030	(piezoelectric or piezo-electric) and ball with rotat\$3	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 17:13
-	22	(piezoelectric or piezo-electric) and ball with rotat\$3 with inside	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 17:14
-	258	(piezoelectric or piezo-electric) and ball with inside	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/05/04 17:14